The Bulk Multicore Architecture for Programmability

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Acknowledgments

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Arch Challenge: Enable a Programmable Environment

- Able to attain high efficiency while relieving the programmer from low-level tasks
- Help minimize chance of (parallel) programming errors





http://iacoma.cs.uiuc.edu/bulkmulticore.pdf

General-purpose multicore for programmability

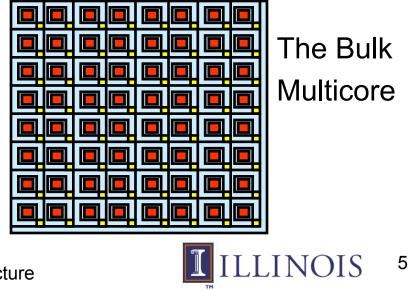
- Novel scalable cache-coherent shared-memory (signatures & chunks)
 - Relieves programmer/runtime from managing shared data
- High-performance sequential memory consistency
 - Provides a more SW-friendly environment
- HW primitives for a low-overhead program dev & debug environment (data-race detection, deterministic replay, address disambiguation)
 - Helps reduce the chance of parallel programming errors
 - Overhead low enough to be "on" during production runs





The Bulk Multicore

- Idea: Eliminate the commit of individual instructions at a time
- Mechanism:
 - By default, processors commit chunks of instructions at a time (e.g. 2,000 dynamic instr)
 - Chunks execute atomically and in isolation (using buffering and undo)
 - Memory effects of chunks summarized in HW signatures
 - Chunks invisible to SW
- Advantages over current:
 - Higher programmability
 - Higher performance
 - Simpler processor hardware





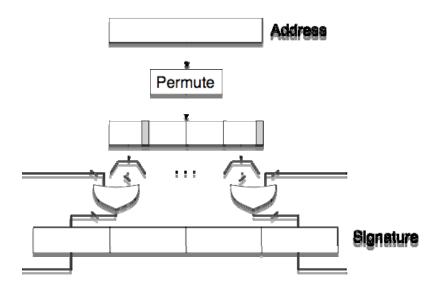
Rest of the Talk

- The Bulk Multicore
- How it improves programmability





• Hardware accumulates the addresses read/written in signatures

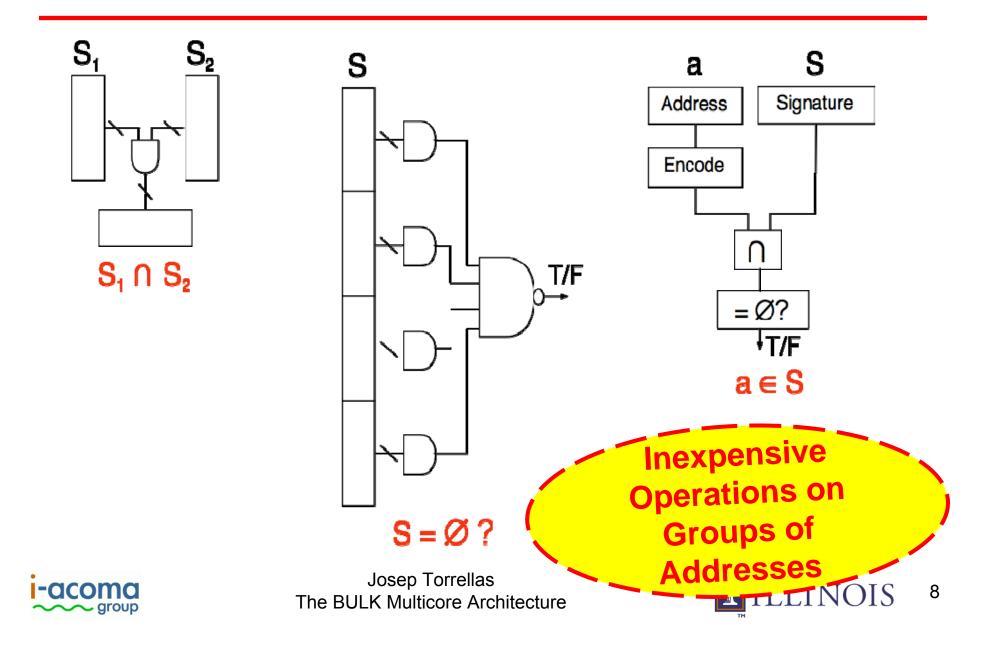


- Read and Write signatures
- Summarize the footprint of a Chunk of code

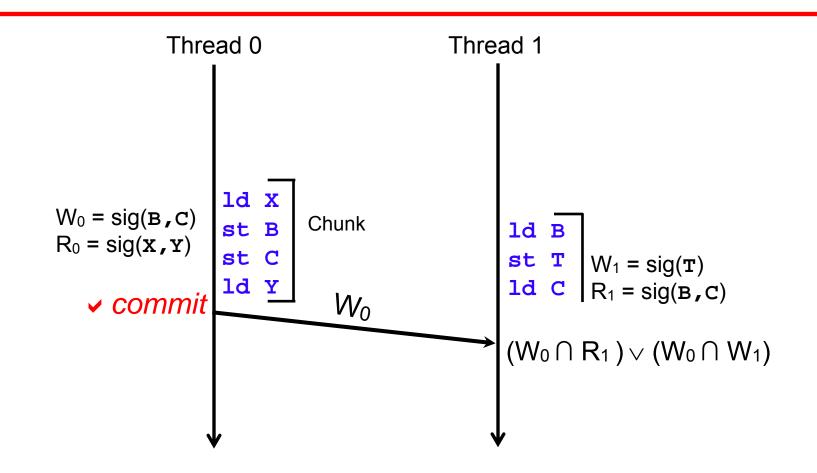




Signature Operations In Hardware



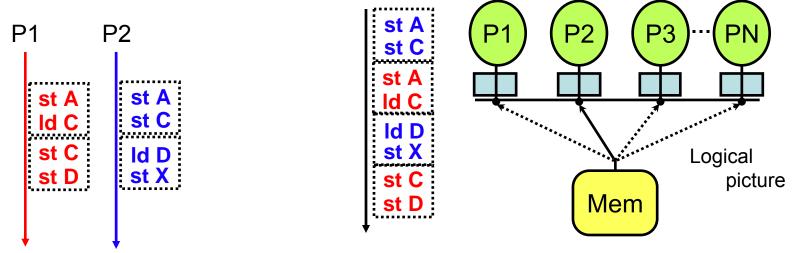
Executing Chunks Atomically & In Isolation: Simple!







- Execute each chunk atomically and in isolation
- (Distributed) arbiter ensures a total order of chunk commits



- Supports Sequential Consistency [Lamport79]:
 - -Low hardware complexity: Need not snoop Id buffer for consistency
 - -High performance: Instructions are fully reordered by HW

loads and stores make it in any order to the sig

Fences are NOOPS





Summary: Benefits of Bulk Multicore

- Gains in HW simplicity, performance, and programmability
- Hardware simplicity:
 - Memory consistency support moved away from core
 - Toward commodity cores
 - Easy to plug-in accelerators
- High performance:
 - HW reorders accesses heavily (intra- and inter-chunk)





- High programmability:
 - Invisible to the programming model/language
 - Supports Sequential Consistency (SC)
 - * Software correctness tools assume SC
 - Enables novel always-on debugging techniques
 - * Only keep per-chunk state, not per-load/store state
 - * Deterministic replay of parallel programs with no log
 - * Data race detection at production-run speed





- Extension: Signatures visible to SW through ISA
 - Enables pervasive monitoring
 - Enables novel compiler opts

Many novel programming/compiler/tool opportunities





Rest of the Talk

- The Bulk Multicore
- How it improves programmability





Supports Sequential Consistency (SC)

- Correctness tools assume SC:
 - Verification tools that prove software correctness
- Under SC, semantics for data races are clear:
 - Easy specifications for safe languages
- Much easier to debug parallel codes (and design debuggers)
- Works with "hand-crafted" synchronization

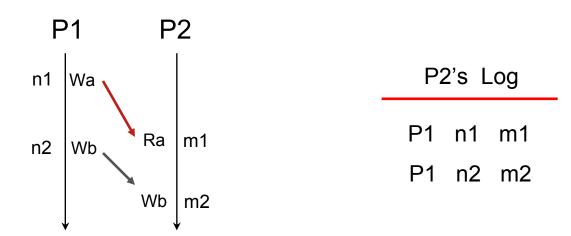




- During Execution: HW records into a log the order of dependences between threads
- The log has captured the "interleaving" of threads
- During Replay: Re-run the program
 - Enforcing the dependence orders in the log





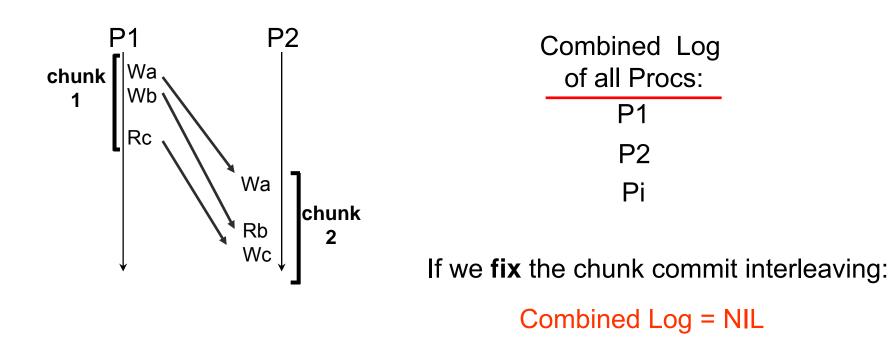


• Potentially large logs





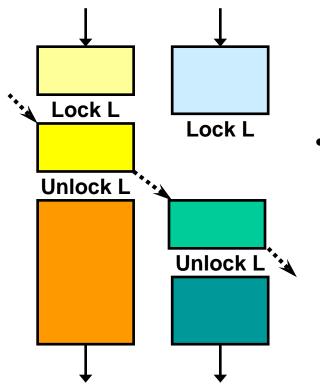
- During Execution:
 - Commit the instructions in chunks, not individually







Data Race Detection at Production-Run Speed [ISCA03]

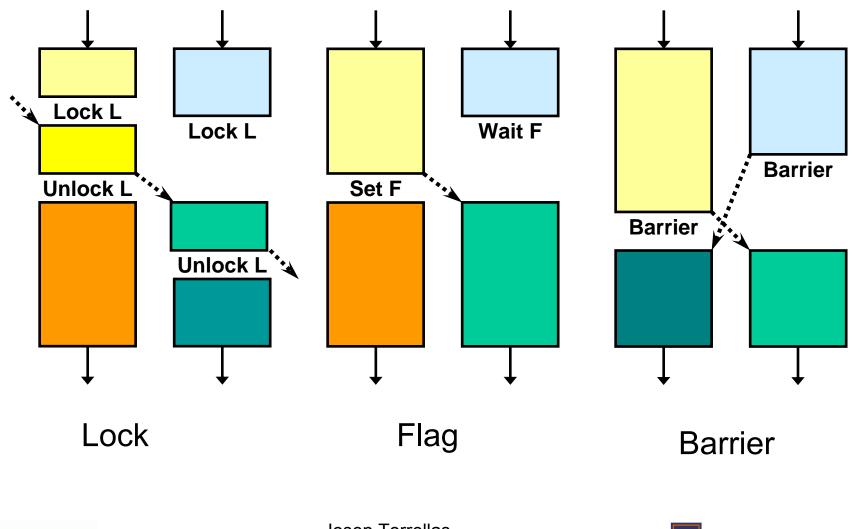


- If we detect communication between...
 - Ordered chunks: not a data race
 - Unordered chunks: data race





Different Synchronization Ops







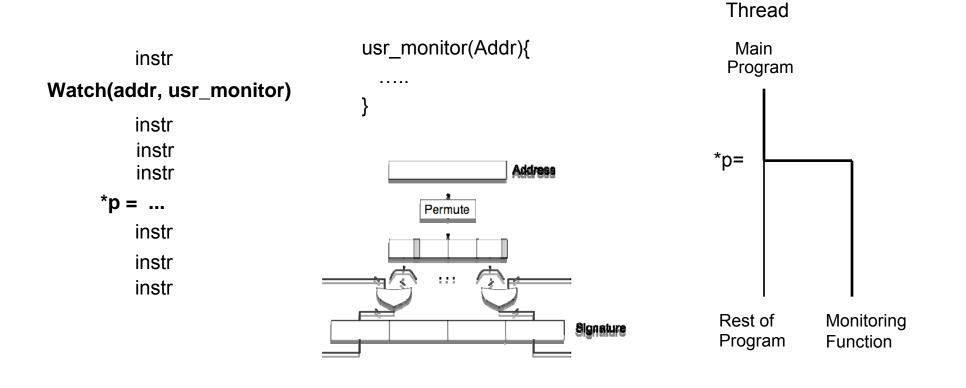
- Extension: Signatures visible to SW through ISA
 - Enables pervasive monitoring [ISCA04]
 - Support numerous watchpoints for free
 - Enables novel compiler opts [ASPLOS08]
 - Function memoization
 - Loop-invariant code motion





Pervasive Monitoring: Attaching a Monitor Function to Address

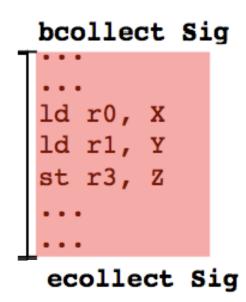
- Watch memory location
- Trigger monitoring function when it is accessed







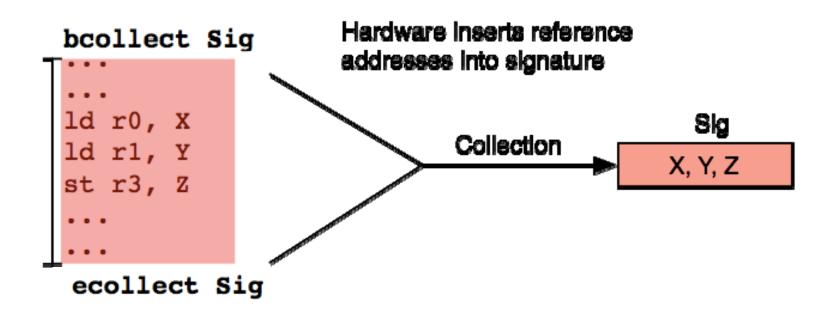
New instruction: Begin/End collecting addresses into sig







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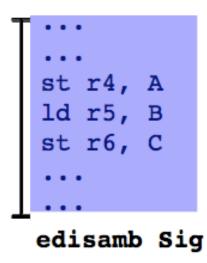






Instruction: Begin/End Disambiguation Against Sig

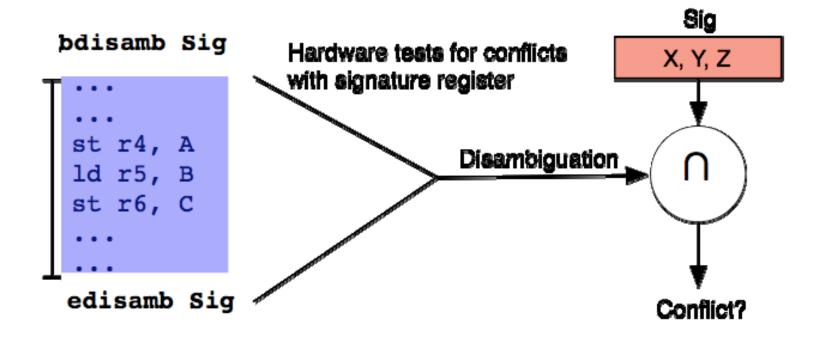
bdisamb Sig







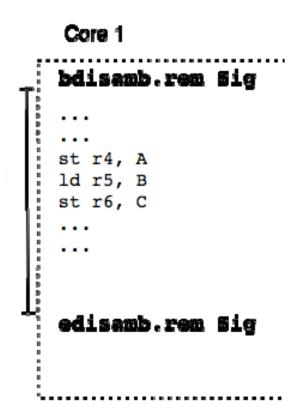
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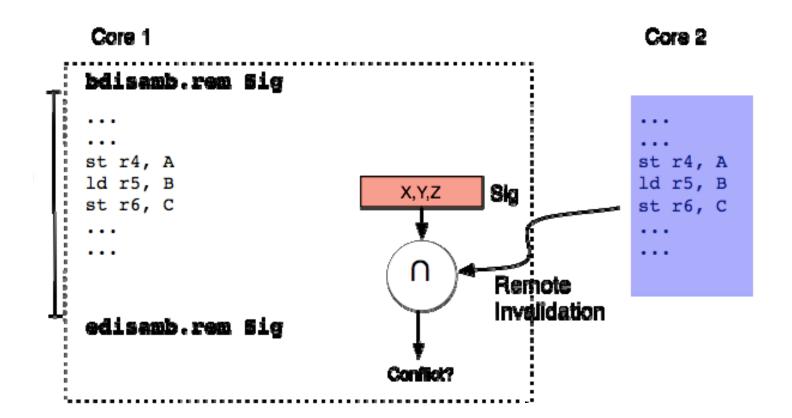
Instruction: Begin/End Remote Disambiguation







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Optimization: Function Memoization

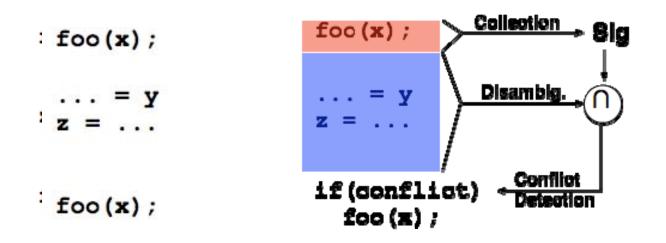
• Goal: skip the execution of functions

foo(x);
... = y
z = ...
foo(x);





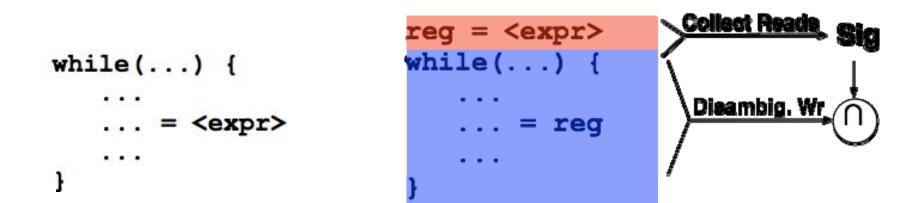
• Goal: skip the execution of functions whose outputs are known







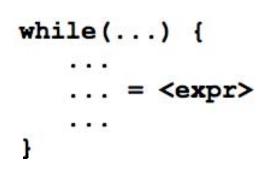
Example Opt: Loop-Invariant Code Motion

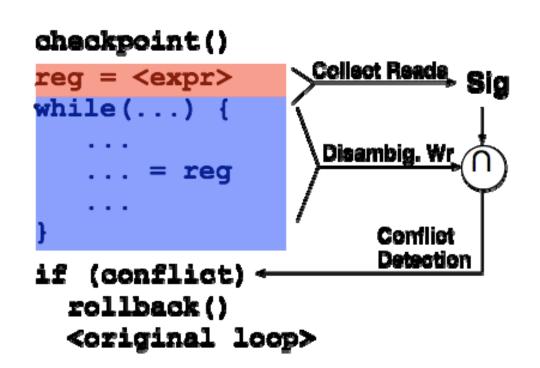






Example Opt: Loop-Invariant Code Motion









Summary: The Bulk Multicore for Year 2015-2018

- 128+ cores/chip, coherent shared-memory (perhaps in groups)
- Simple HW with commodity cores
 - Memory consistency checks moved away from the core
- High performance shared-memory programming model
 - Execution in programmer-transparent chunks
 - Signatures for disambiguation, cache coherence, and compiler opts
- High programmability:
 - Sequential consistency
 - Sophisticated always-on development support
 - Deterministic replay of parallel programs with no log (DeLorean)
 - Data race detection for production runs (*ReEnact*)
 - Pervasive program monitoring (*iWatcher*)





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